

Information Sheet for Exam 2**1. Jacobian Matrix of a C^1 Function**

The Jacobian matrix of a function $\Phi: D \rightarrow \mathbb{R}^2$ defined on an open subset, D , of \mathbb{R}^2 by

$$\Phi \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} x(u, v) \\ y(u, v) \end{pmatrix} \quad \text{for all } \begin{pmatrix} u \\ v \end{pmatrix} \in D,$$

where x and y are C^1 scalar fields on D , is given by

$$D\Phi(u, v) = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix},$$

where the partial derivatives are evaluated at (u, v) in D .

2. Jacobian Determinant of a C^1 Function

The Jacobian determinant, or simply the Jacobian, of a C^1 function $\Phi: D \rightarrow \mathbb{R}^2$ is the determinant of the Jacobian matrix $D\Phi(u, v)$. We denote it by $\frac{\partial(x, y)}{\partial(u, v)}$.

3. Tangent Line Approximation to a C^1 Path

The tangent line approximation to a C^1 path $\sigma: [a, b] \rightarrow \mathbb{R}^n$ at $\sigma(t_o)$, for some $t_o \in (a, b)$, is the straight line given by

$$L(t) = \sigma(t_o) + (t - t_o)\sigma'(t_o) \quad \text{for all } t \in \mathbb{R}$$

4. Arc Length

Let $\sigma: [a, b] \rightarrow \mathbb{R}^n$ be a C^1 parametrization of a curve C . The arc length of C is given by

$$\ell(C) = \int_a^b \|\sigma'(t)\| dt.$$

5. Path Integral

Let $f: U \rightarrow \mathbb{R}$ be a continuous scalar field defined on some open subset of \mathbb{R}^n . Suppose there is a C^1 curve C contained in U . Then the integral of f over C is given by

$$\int_C f ds = \int_a^b f(\sigma(t))\|\sigma'(t)\| dt,$$

for any C^1 parametrization, $\sigma: [a, b] \rightarrow \mathbb{R}^n$ of the curve C .

6. Line Integral

Let $F: U \rightarrow \mathbb{R}^n$ denote a continuous vector field defined on some open subset, U , of \mathbb{R}^n . Suppose there is a C^1 curve, C , contained in U . Then, the line integral of F over C is given by

$$\int_C F \cdot T \, ds = \int_a^b F(\sigma(t)) \cdot \sigma'(t) \, dt,$$

for any C^1 parametrization, $\sigma: [a, b] \rightarrow \mathbb{R}^n$, of the curve C . Here T denotes the tangent unit vector to the curve, and it is given by

$$T(t) = \frac{1}{\|\sigma'(t)\|} \sigma'(t) \quad \text{for all } t \in (a, b).$$

If $F = P \hat{i} + Q \hat{j} + R \hat{k}$, where P , Q and R are C^1 scalar fields defined on U ,

$$\int_C F \cdot T \, ds = \int_C P \, dx + Q \, dy + R \, dz.$$

The expression $P \, dx + Q \, dy + R \, dz$ is called a differential 1-form.

7. Flux

Let $F = P \hat{i} + Q \hat{j}$, where P and Q are continuous scalar fields defined on an open subset, U , of \mathbb{R}^2 . Suppose there is a C^1 simple closed curve C contained in U . Then the flux of F across C is given by

$$\int_C F \cdot \hat{n} \, ds = \int_C P \, dy - Q \, dx.$$

Here, \hat{n} denotes a unit vector perpendicular to C and pointing to the outside of C .

8. Green's Theorem.

The Fundamental Theorem of Calculus,

$$\int_M d\omega = \int_{\partial M} \omega,$$

takes the following form in two-dimensional Euclidean space:

Let R denote a region in \mathbb{R}^2 bounded by a simple closed curve, ∂R , made up of a finite number of C^1 paths traversed in the counterclockwise sense. Let P

and Q denote two C^1 scalar fields defined on some open set containing R and its boundary, ∂R . Then,

$$\int_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial R} P dx + Q dy.$$

9. The Change of Variables Theorem

Let R denote a region in the xy -plane and D a region in the uv -plane. Suppose that there is a change of coordinates function $\Phi: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that maps D onto R . Then, for any continuous function, f , defined on R ,

$$\int_R f(x, y) dx dy = \int_D f(\Phi(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv,$$

where $\frac{\partial(x, y)}{\partial(u, v)}$ denotes the determinant of the Jacobian matrix of Φ .

10. Polar Coordinates

Suppose the change of variable

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

maps the region D in the $r\theta$ -plane onto the region R in the xy -plane in a one-to-one fashion. Then, for any continuous function, f , defined on R ,

$$\int_R f(x, y) dx dy = \int_D f(r \cos \theta, r \sin \theta) r dr d\theta.$$