

## Solutions to Assignment #5

1. Suppose that  $X_t$  satisfies the *difference inequality*

$$|X_{t+1}| \leq \eta |X_t| \quad \text{for } t = 0, 1, 2, 3, \dots$$

where  $0 < \eta < 1$ . Prove that  $\lim_{t \rightarrow \infty} X_t = 0$ .

*Solution:* For  $t = 0$  we get

$$|X_1| \leq \eta |X_0|.$$

Similarly, for  $t = 1$ , we get

$$|X_2| \leq \eta |X_1| \leq \eta^2 |X_0|,$$

by the previous inequality. We may, therefore, proceed by induction on  $n$  to prove that

$$|X_n| \leq \eta^n |X_0| \quad \text{for } n = 1, 2, 3, \dots$$

We therefore have that

$$0 \leq |X_t| \leq \eta^t |X_0|, \quad \text{for } t = 0, 1, 2, \dots,$$

where  $0 < \eta < 1$ , so that

$$\lim_{t \rightarrow \infty} \eta^t = 0.$$

It then follows by the Squeeze Theorem, or the Sandwich Theorem, that

$$\lim_{n \rightarrow \infty} |X_n| = 0.$$

Hence,  $\lim_{t \rightarrow \infty} X_t = 0$ .  $\square$

2. The *Principle of Linearized Stability* for the difference equation

$$N_{t+1} = f(N_t)$$

states that, if  $f$  is differentiable at a fixed point  $N^*$  and

$$|f'(N^*)| < 1,$$

then  $N^*$  is an asymptotically stable equilibrium solution.

In this problem we use the Principle of Linearized stability to analyze the following population model:

$$N_{t+1} = \frac{kN_t}{b + N_t}$$

where  $k$  and  $b$  are positive parameters.

- (a) Write the model in the form  $N_{t+1} = f(N_t)$  and give the fixed points of  $f$ . What conditions of  $k$  and  $b$  must be imposed in order to ensure that the model will have a non-negative steady state?

*Solution:*  $f(x) = \frac{kx}{b+x}$  in this case, so that the fixed points of  $f$  are solutions to the equation

$$\frac{kx}{b+x} = x,$$

or

$$\frac{kx}{b+x} - x = 0.$$

Factoring the last expression we get

$$x \left( \frac{k}{b+x} - 1 \right) = 0.$$

Thus, either  $x = 0$  or  $\frac{k}{b+x} - 1 = 0$ . Solving the last expression for  $x$  we obtain  $x = k - b$ . Thus, the fixed point of  $f$  are

$$N^* = 0 \quad \text{and} \quad N^* = k - b.$$

For the second fixed point to be nonnegative, it must be the case that  $b \leq k$ .  $\square$

- (b) Determine the stability of the equilibrium points found in part (a).

*Solution:* We apply the Principle of Linearized Stability. Compute

$$f'(x) = \frac{bk}{(b+x)^2}.$$

Then,  $f'(0) = \frac{bk}{b^2} = \frac{k}{b} \geq 1$  since  $b \leq k$ , by part (a). Thus, if  $b < k$ , then  $N^* = 0$  is unstable, by the Principle of Linearized Stability. If  $b = k$ , the Principle of Linearized Stability does not apply.

Similarly, since  $f'(k-b) = \frac{bk}{k^2} = \frac{b}{k} \leq 1$  since  $b \leq k$ , by part (a). Thus, if  $b < k$ , then  $N^* = k - b$  is asymptotically stable, by the Principle of Linearized Stability. On the other hand, if  $b = k$ , the Principle of Linearized Stability does not apply.  $\square$

3. [Problems 1.3.6 (d)(e) on page 29 in Allman and Rhodes]

- (d) Determine the equilibrium points of
- $\Delta P = aP - bP^2$
- .

*Solution:* Solve the equation  $aP - bP^2 = 0$ ,  $P(a - bP) = 0$  to obtain  $P^* = 0$  or  $P^* = a/b$  (here we are assuming that  $b \neq 0$ ).  $\square$

- (e) Determine the equilibrium points of
- $P_{t+1} = cP_t - dP_t^2$
- .

*Solution:* Here we find the fixed points of  $f(P) = cP - dP^2$ ; that is, we solve the equation  $f(P) = P$ , or  $cP - dP^2 = P$ . To solve this equation, we rewrite it as

$$(c - 1)P - dP^2 = 0,$$

from which we get, after factoring that

$$P[(c - 1) - dP] = 0.$$

Thus,  $P^* = 0$  or  $P^* = (c - 1)/d$ , for  $d \neq 0$ .  $\square$

4. [Problems 1.3.7 (d)(e) on page 29 in Allman and Rhodes] For each of the equations in the previous problem, use the principle of linearized stability to determine the stability of each of the equilibrium points.

- (d)
- $\Delta P = aP - bP^2$
- .

*Solution:* Here,  $f(P) = P + aP - bP^2$ , so that  $f'(P) = 1 + a - 2bP$ . Thus,  $f'(0) = 1 + a$ . Hence,  $P^* = 0$  is stable for  $-2 < a < 0$ , and unstable for  $a > 0$  or  $a < -2$ .

Similarly, since  $f'(a/b) = 1 + a - 2b(a/b) = 1 - a$ ,  $P^* = a/b$  is stable for  $0 < a < 2$ , and unstable for  $a < 0$  or  $a > 2$ .  $\square$

- (e)
- $P_{t+1} = cP_t - dP_t^2$
- .

*Solution:* In this case,  $f(P) = cP - dP^2$  and so  $f'(P) = c - 2dP$ .

Thus,  $f'(0) = c$  and so  $P^* = 0$  is stable if  $|c| < 1$  and unstable if  $|c| > 1$ .

Similarly, since  $f'((c - 1)/d) = 2 - c$ ,  $P^* = (c - 1)/d$  is stable if  $1 < c < 3$ , and unstable if  $c < 1$  or  $c > 3$ .  $\square$

5. Problems 1.3.11 (a)(b)(c)(d) on page 30 in Allman and Rhodes.

*Note:* The code for the MATLAB<sup>®</sup> program `onpop` may be downloaded from the courses website at <http://pages.pomona.edu/~ajr04747>.

Many biological processes involve *diffusion*. A simple example is the passage of oxygen from the lung into the bloodstream (and the passage of carbon dioxide in the opposite direction). A simple model views the lung as a single compartment with oxygen concentration  $L$  and the bloodstream an adjoining compartment with oxygen concentration  $B$ . If, for simplicity, we assume that

the compartments both have volume 1, then in the time span of a single breath the total oxygen  $K = L + B$  is constant. If we think of a very *small* time interval, then the increase of  $B$  over this time interval will be proportional to the difference between  $L$  and  $B$ . That is,

$$\Delta B = r(L - B). \quad (1)$$

(This experimental fact is sometimes called *Fick's Law*.)

- (a) In what range must the parameter  $r$  be for this model to be meaningful?  
*Solution:*  $0 < r < 1$  since (i) the oxygen concentration in the bloodstream must increase (with oxygen coming from the lungs) if  $L > B$ , and decrease if  $B > L$ ; and (ii) even if  $B$  is very low, it can not increase by an amount larger than the amount of oxygen available in the lungs.  $\square$
- (b) Use the fact that  $L + B = K$  to write the model (1) using only the parameters  $r$  and  $K$  to describe  $\Delta B$  in terms of  $B$ .  
*Solution:* Solving for  $L$  in  $L + B = K$  and substituting into (1) yields

$$\Delta B = r(K - 2B). \quad \square$$

- (c) For  $r = 0.1$  and  $K = 1$ , and a variety of choices for  $B_o$ , investigate the MATLAB<sup>®</sup> program `onepop`. How do things change as a different value of  $r$  is used?  
*Solution:* For any initial condition  $B_o$ , the solutions tend to  $K/2 = 0.5$  as  $t \rightarrow \infty$ . The result is the same for any  $r$  with  $0 < r < 1$ .  $\square$
- (d) Algebraically, find the equilibrium point  $B^*$  for (1). Does this fit with what you saw in part (c)? Can you explain this result intuitively?  
*Solution:* We apply the Principle of Linearized Stability. In this case  $f(B) = B + r(K - 2B)$ , so that the fixed point of  $f$  is  $B$  such that  $f(B) = B$ , which yields  $B^* = K/2$ . To determine whether or not  $B^*$  is stable, compute  $f'(B) = 1 - 2r$ . Thus,  $B^* = K/2$  is stable if  $|1 - 2r| < 1$  or  $0 < r < 1$ . This is precisely what we saw in the numerical experiments in part (c). Intuitively, as time goes on, after many breaths, the oxygen concentration in the bloodstream should reach a steady state which is equal to the amount of oxygen in the lungs.  $\square$