

Assignment #6

Due on Wednesday, March 30, 2011

Read Section I.7 on *Autonomous Systems–Generalities*, pp. 37–46, in Hale’s text.

Read Section I.8 on *Autonomous Systems–Limit Sets, Invariant Sets*, pp. 46–49, in Hale’s text.

Read Chapter 4 on *Continuous Dynamical Systems*, starting on page 47, in the class lecture notes.

Background and Definitions

Let U denote an open subset of \mathbb{R}^N and $F: U \rightarrow \mathbb{R}^N$ be a C^1 vector field. Let J_p denote the maximal interval of existence for the IVP

$$\begin{cases} \frac{dx}{dt} = F(x); \\ x(0) = p. \end{cases} \quad (1)$$

- (*Periodic Solutions*) A solution $u: J \rightarrow U$ of the differential equation in (1), which is not an equilibrium solution, is said to be periodic if there exists a positive number, τ , such that

$$u(t + \tau) = u(t), \quad \text{for all } t \in J \text{ with } t + \tau \in J. \quad (2)$$

The smallest positive number, τ , for which (2) holds true is called the period of u .

- (*Cycles*) In this problem set we will look at a condition that will guarantee that the solution to the IVP in (1) is periodic. We will also see that periodic solutions must be defined for all $t \in \mathbb{R}$. If the IVP in (1) has a periodic solution of period T , $u_p: \mathbb{R} \rightarrow U$, then the orbit of p , γ_p , is a closed curve parametrized by

$$u_p: [0, T] \rightarrow U.$$

The closed orbit, γ_p , is called a cycle.

Do the following problems

In problems 1 through 4, $u_p: J_p \rightarrow U$ denotes the unique solution to the IVP in (1).

1. Assume that there exist t_1 and t_2 in J_p such that $t_1 \neq t_2$ and

$$u_p(t_1) = u_p(t_2).$$

Prove that there exists $\tau > 0$ such that

$$u_p(t) = u_p(t + \tau), \quad \text{for all } t \in J_p. \quad (3)$$

2. Prove that (3) implies that $J_p = \mathbb{R}$; that is, $u_p(t)$ is defined for all $t \in \mathbb{R}$.

Suggestion: Write $J_p = (a, b)$ and assume, by way of contradiction, that $b \in \mathbb{R}$. Let (t_m) be a sequence in (a, b) such that t_m increases to b as $m \rightarrow \infty$ and $t_m - \tau \in J_p$ for all $m \in \mathbb{N}$. Show that $\lim_{m \rightarrow \infty} u_p(t_m)$ exists in U .

3. Assume that p is not an equilibrium point of the system in (1) and define

$$T = \inf\{\tau > 0 \mid (3) \text{ holds true}\}. \quad (4)$$

Prove that $T > 0$ and $u_p(t) = u_p(t + T)$ for all $t \in \mathbb{R}$.

Suggestion: Argue by contradiction; that is, assume that there exists a sequence, (τ_m) , of positive numbers such that τ_m decreases to 0 and

$$u_p(t + \tau_m) = u_p(t), \quad \text{for all } t \in \mathbb{R}.$$

Consider $\frac{u_p(t + \tau_m) - u_p(t)}{\tau_m}$ as $m \rightarrow \infty$.

4. Assume that p is not an equilibrium point of the system in (1), and that $u_p: \mathbb{R} \rightarrow U$ is a periodic solution on the IVP in (1). Show that the orbit, γ_p , is a cycle.

Suggestion: Let T denote the period of the u_p . Show that

$$u_p: [0, T] \rightarrow U$$

is a parametrization of γ_p ; that is,

- $u_p: [0, T) \rightarrow U$ is one-to-one, and
- $u_p([0, T]) = \gamma_p$.

5. Let $\theta: \mathbb{R} \times U \rightarrow U$ be a dynamical system in U . For $p \in U$, assume that γ_p is a cycle. Prove that $\omega(\gamma_p) = \gamma_p$, and $\alpha(\gamma_p) = \gamma_p$.

Suggestion: Show that $\gamma_p \subseteq \omega(\gamma_p)$ and $\omega(\gamma_p) \subseteq \gamma_p$.