

## Assignment #17

Due on Wednesday, November 12, 2014

**Read** Section 4.3 on *Matrix Representation of Linear Functions* in the class lecture notes at <http://pages.pomona.edu/~ajr04747/>

**Read** Section 2.2 on *Linear Transformations between Finite Dimensional Vector Spaces* in Damiano and Little (pp. 73–81)

**Read** Section 2.3 on *Kernel and Image* in Damiano and Little (pp. 84–92)

**Do** the following problems

1. Let  $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a function satisfying

$$f \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 3 \end{pmatrix}, \quad f \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 1 \end{pmatrix} \quad \text{and} \quad f \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}.$$

- (a) Show that  $f$  cannot be linear.
- (b) What would  $f \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  be if  $f$  was a linear function?
2. Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a linear function satisfying

$$T \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} \quad \text{and} \quad T \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -5 \\ 1 \\ 1 \end{pmatrix}.$$

- (a) Find the matrix representation for  $T$  relative to the standard bases in  $\mathbb{R}^2$  and  $\mathbb{R}^3$ .
- (b) Give formula for computing  $T \begin{pmatrix} x \\ y \end{pmatrix}$  for any  $\begin{pmatrix} x \\ y \end{pmatrix}$  in  $\mathbb{R}^2$ .
- (c) Compute  $T \begin{pmatrix} 4 \\ 7 \end{pmatrix}$ .
3. Let  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  denote the linear transformation defined in Problem ??.

- (a) Determine the image,  $\mathcal{I}_T = \{w \in \mathbb{R}^3 \mid w = T(v) \text{ for some } v \in \mathbb{R}^2\}$ , of  $T$ .
- (b) Find a basis for  $\mathcal{I}_T$  and compute  $\dim(\mathcal{I}_T)$ .

4. The projection  $P_u: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  onto the direction of the unit vector  $u$  in  $\mathbb{R}^3$  is given by

$$P_u(v) = \langle v, u \rangle u \quad \text{for all } v \in \mathbb{R}^3,$$

where  $\langle \cdot, \cdot \rangle$  denotes the Euclidean inner product in  $\mathbb{R}^3$ . We proved in class that  $P_u$  is a linear function.

- (a) For  $u = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ , give the matrix representation for  $P_u$  relative to the standard basis in  $\mathbb{R}^3$ .

- (b) For  $u$  as defined in the previous part, determine the null space,

$$\mathcal{N}_{P_u} = \{v \in \mathbb{R}^3 \mid P_u(v) = \mathbf{0}\},$$

of  $P_u$ .

- (c) Find a basis for  $\mathcal{N}_{P_u}$  and compute  $\dim(\mathcal{N}_{P_u})$ .

5. Let  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  and  $R: \mathbb{R}^m \rightarrow \mathbb{R}^k$  denote two linear functions. The composition of  $R$  and  $T$ , denoted by  $R \circ T$ , is the function  $R \circ T: \mathbb{R}^n \rightarrow \mathbb{R}^k$  defined by

$$R \circ T(v) = R(T(v)) \quad \text{for all } v \in \mathbb{R}^n.$$

- (a) Prove that the composition  $R \circ T$  is a linear function from  $\mathbb{R}^n$  to  $\mathbb{R}^k$ .
- (b) Show that  $\mathcal{N}_T \subseteq \mathcal{N}_{R \circ T}$ .
- (c) Show that  $\mathcal{I}_{R \circ T} \subseteq \mathcal{I}_R$ .