

Assignment #20

Due on Friday, November 21, 2014

Read Section 4.3 on *Matrix Representation of Linear Functions* in the class lecture notes at <http://pages.pomona.edu/~ajr04747/>

Read Section 4.4, on *Compositions*, in the class lecture notes at <http://pages.pomona.edu/~ajr04747/>

Read Section 2.3 on *Kernel and Image* in Damiano and Little (pp. 84–92)

Read Section 2.4 on *Applications of the Dimension Theorem* in Damiano and Little (pp. 95–103)

Background and Definitions

- **Null Space of a Linear Transformation.** Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ denote a linear transformation. The null space of T , denoted by \mathcal{N}_T , is the set

$$\mathcal{N}_T = \{v \in \mathbb{R}^n \mid T(v) = \mathbf{0}\}.$$

Note: In the text, the null space of T is called the kernel of T , and is denoted by $\text{Ker}(T)$.

- **Image.** Given a function $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$, the image of T , denoted by \mathcal{I}_T , is the set

$$\mathcal{I}_T = \{w \in \mathbb{R}^m \mid w = T(v), \text{ for some } v \in \mathbb{R}^n\}.$$

Note: In the text, the image of T is denoted by $\text{Im}(T)$.

If T is linear, then \mathcal{I}_T is a subspace of \mathbb{R}^m .

- **The Dimension Theorem.** Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then,

$$\dim(\mathcal{N}_T) + \dim(\mathcal{I}_T) = n. \quad (1)$$

Do the following problems

1. In this problem and problems (2) and (3) you will be proving the Dimension Theorem as stated in (1).

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Show that if $\mathcal{N}_T = \mathbb{R}^n$, then T must be the zero transformation. What is \mathcal{I}_T in this case? Verify that (1) holds true in this case.

2. Suppose that $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation that is not the zero function. Put $k = \dim(\mathcal{N}_T)$.
- (a) Explain why $k < n$.
 - (b) Let $\{w_1, w_2, \dots, w_k\}$ be a basis for \mathcal{N}_T . Show that there exist vectors v_1, v_2, \dots, v_r in \mathbb{R}^n such that $\{w_1, w_2, \dots, w_k, v_1, v_2, \dots, v_r\}$ is a basis for \mathbb{R}^n . What is r in terms of n and k ?
3. Let T , w_1, w_2, \dots, w_k and v_1, v_2, \dots, v_r be as in Problem 2.
- (a) Show that the set $\{T(v_1), T(v_2), \dots, T(v_r)\}$ is a basis for \mathcal{I}_T , the image of T .
 - (b) Prove the Dimension Theorem.
4. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation.
- (a) Prove that T is one-to-one if and only if $\dim(\mathcal{I}_T) = n$.
 - (b) Prove that T is onto if and only if $\dim(\mathcal{I}_T) = m$.
5. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be given by

$$T(v) = Av, \quad \text{for all } v \in \mathbb{R}^3,$$

where A is the 3×3 matrix given by

$$A = \begin{pmatrix} 0 & 1 & 1 \\ -1 & 0 & 1 \\ -1 & -1 & 0 \end{pmatrix}.$$

Determine whether or not T is

- (a) one-to-one;
- (b) onto;
- (c) invertible.