

QUALITATIVE ANALYSIS

Overview

1. Simplified System of ODEs
2. Solution and Analysis Approaches
3. Graphical Analysis: Finding Nullclines and Equilibria
4. Determining Stability Analytically

Qualitative Analysis

Reduction to Two ODEs

Letting

$$p = fk$$

$$m = k(k_{-1} + k_2) - k_1$$

$$n = k(k_{-1} + k_3) - k_1$$

the new ODE system becomes

$$\frac{dE}{dt} = \text{_____} (1)$$

$$\frac{dT}{dt} = \text{_____} (2)$$

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Solution and Analysis Approaches

Question: What is the next step?

Answer: We want to “solve” this system. There are three main approaches to understanding the solutions of a system of ODEs:

1. Find the _____(1)
2. Do a _____(2)
3. Find a _____(3)

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Finding Nullclines

Step 1: Find nullclines algebraically.

1. Set

$$\begin{aligned}\frac{dE}{dt} &= \text{—————(1)} \\ \frac{dT}{dt} &= \text{—————(2)}\end{aligned}$$

continue \Rightarrow

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Finding Nullclines (continued)

2. Solve for E -nullcline:

$$E = \text{_____} (3)$$

3. Solve for T -nullcline:

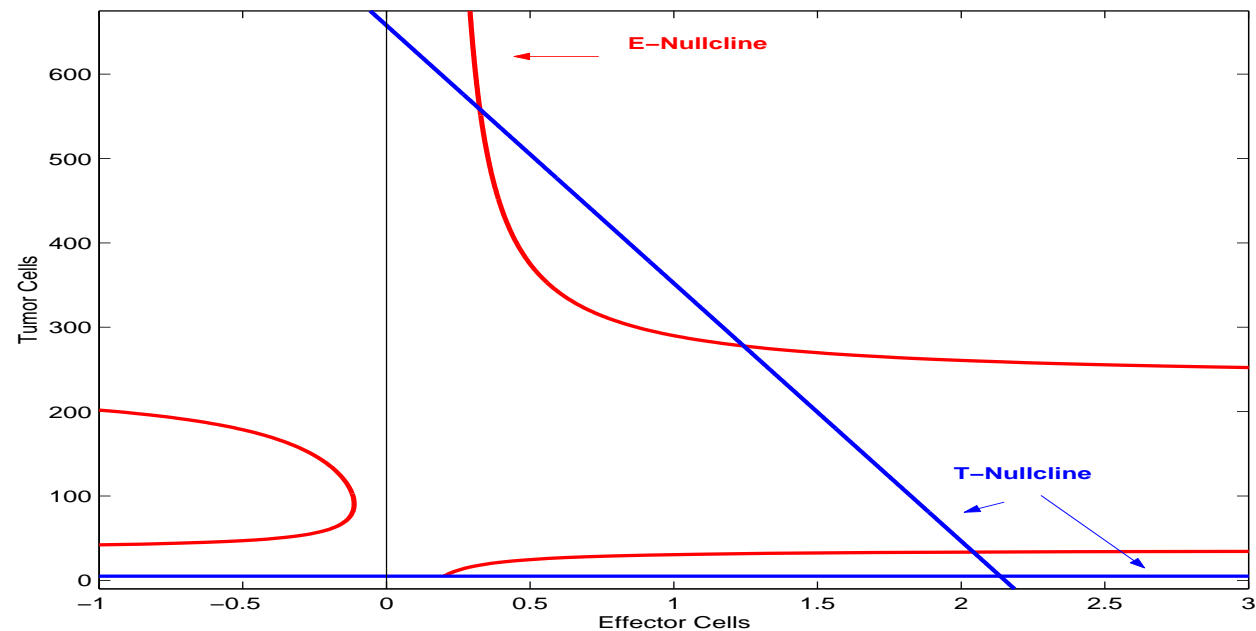
$$E = \text{_____} (4)$$

or $T = \text{_____} (5)$

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Finding Equilibria

Step 2: Find _____(1) graphically.



Step 3: Determine the _____(2) graphically.

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Summary of Graphical Analysis

From our *graphical* analysis of the equilibria we can conclude that **for the particular parameter set** used in the example:

- Point A (tumor-free) is an _____(1).
- Point B (low tumor burden) may be a _____(2) or a _____(3), and may be _____(4) or _____(5), in which case nearby points might converge to a _____(6).
- Point C (non-zero tumor burden) is _____(7) (and may be a _____(8)).
- Point D (high tumor burden) is _____(9).

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Analytic Determination of Stability

General Procedure

Step 1: Specify an _____(1) point to analyze. Call it (x_0, y_0) .

Step 2: _____(2) the system about the equilibrium point by evaluating the Jacobian at that point.

Step 3: Find the _____(3) of the Jacobian to determine the stability properties of point (x_0, y_0) .

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The Stability of a Nearly Linear System

Theorem: from Borrelli and Coleman [BC98] Suppose that \mathbf{J} is an $n \times n$ matrix of real constants. Furthermore, suppose $\vec{\mathbf{P}}(\vec{\mathbf{x}})$ is a vector-valued function that is continuously differentiable in an open ball $B_r(\vec{\mathbf{p}})$, that $\vec{\mathbf{P}}(\vec{\mathbf{p}}) = 0$, and that $\vec{\mathbf{P}}(\vec{\mathbf{x}})$ has order at least 2 at $\vec{\mathbf{p}}$. Then the *nearly linear* system:

$$\frac{d\vec{\mathbf{x}}}{dt} = \mathbf{J}(\vec{\mathbf{x}} - \vec{\mathbf{p}}) + \vec{\mathbf{P}}(\vec{\mathbf{x}})$$

has the following properties:

1. The system is **asymptotically stable** at $\vec{\mathbf{p}}$ if all eigenvalues of \mathbf{J} have negative real parts.
2. The system is **unstable** at $\vec{\mathbf{p}}$ if there is at least one eigenvalue of \mathbf{J} with positive real part.

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The Stability of a Nearly Linear System (continued)

Note: The matrix, \mathbf{J} , is the _____ (1) of the nonlinear system, evaluated at the _____ (2) \vec{p} .

Unfortunately, this theorem doesn't tell us anything about the equilibrium if all of the eigenvalues of \mathbf{J} have real part _____ (3), but at least one of them has real part _____ (4).

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Analytic Determination of Stability: General Example

Example: Given the ODE system

$$\begin{aligned}\frac{dx}{dt} &= F_1(x, y) \\ \frac{dy}{dt} &= F_2(x, y)\end{aligned}$$

the linearized system at a point (x_0, y_0) is

$$\begin{bmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \end{bmatrix} = \mathbf{J} \begin{bmatrix} x \\ y \end{bmatrix}, \quad \text{or with vector notation: } \dot{\vec{x}} = \mathbf{J}\vec{x}$$

where \mathbf{J} is the Jacobian of the system evaluated at (x_0, y_0) .

continued \Rightarrow

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Analytic Determination of Stability: General Example (continued)

The Jacobian matrix **J** is given by

$$\mathbf{J} = \begin{bmatrix} \text{---(1)---} & \text{---(2)---} \\ \text{---(3)---} & \text{---(4)---} \end{bmatrix}$$

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Example: Jacobian for Point A

- Plug $T = 0$ into E -nullcline equation $\Rightarrow E = s/d$. Therefore, $(x_0, y_0) = (s/d, 0)$.
- Determine the Jacobian.

$$\mathbf{J} = \begin{bmatrix} \text{---(1)---} & \text{---(2)---} \\ \text{---(3)---} & \text{---(4)---} \end{bmatrix}$$

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Example: Eigenvalues of Jacobian for Point A

Because **J** is a _____(1) matrix, the eigenvalues are on the _____(2). Therefore, eigenvalues λ_1 and λ_2 are

$$\lambda_1 = \text{_____}(3)$$

$$\lambda_2 = \text{_____}(4)$$

Note:

- λ_1 is always _____(5).
- λ_2 is _____(6) if and only if _____(7)