## Assignment #7

## Due on Friday, November 10, 2017

**Read** Chapter 5, *Optimization Problems with Constraints*, in the class lecture notes at http://pages.pomona.edu/~ajr04747/

**Read** Chapter 4, *Isoperimetric Problems*, in *Calculus of Variations* by Robert Weinstock. **Do** the following problems

1. Let  $V = C^1([a, b], \mathbb{R}^2)$ ; so that, the elements of V are vector-valued functions

$$(x,y)\colon [a,b]\to \mathbb{R}^2,$$

whose values are denoted by (x(t), y(t)), for  $t \in [a, b]$ , where the functions  $x : [a, b] \to \mathbb{R}$ and  $y : [a, b] \to \mathbb{R}$  are differentiable functions of  $t \in (a, b)$ , with continuous derivatives  $\dot{x}$  and  $\dot{y}$  (the dot on top of a variable name indicates derivative with respect to t). We denote by  $V_o$  the space of vector valued functions  $(\eta_1, \eta_2) \in V$  such that

$$\eta_1(a) = \eta_1(b) = \eta_2(a) = \eta_2(b) = 0.$$

- (a) Show that V is a vector space.
- (b) Show that  $V_o$  is a subspace of V
- 2. Let V be as in Problem 1. For  $(x, y) \in V$ , define

$$\|(x,y)\| = \max_{a\leqslant t\leqslant b} |x(t)| + \max_{a\leqslant t\leqslant b} |y(t)| + \max_{a\leqslant t\leqslant b} |\dot{x}(t)| + \max_{a\leqslant t\leqslant b} |\dot{y}(t)|.$$

Verify that  $\|(\cdot, \cdot)\|$  defines a norm in V.

3. Let V and  $V_o$  be as in Problem 1. Consider a function  $F: [a, b] \times \mathbb{R}^4 \to \mathbb{R}$  whose values are denoted by F(t, x, y, p, q) for  $t \in [a, b]$  and real variables x, y, p and q. We assume that the F has partial derivatives

$$F_x(t, x, y, p, q), F_y(t, x, y, p, q), F_p(t, x, y, p, q) \text{ and } F_q(t, x, y, p, q),$$

which are assumed to be continuous on  $[a, b] \times \mathbb{R}^4$ . Define the functional  $J: V \to \mathbb{R}$  by

$$J((x,y)) = \int_{a}^{b} F(t,x(t),y(t),\dot{x}(t),\dot{y}(t)) \, dt, \quad \text{for all } (x,y) \in V.$$
(1)

For  $(x, y) \in V$  and  $(\eta_1, \eta_2) \in V_o$ , define  $g \colon \mathbb{R} \to \mathbb{R}$  by

$$g(s) = J((x, y) + s((\eta_1, \eta_2)) = J((x + s\eta_1, y + s\eta_2)),$$
 for all  $s \in \mathbb{R}$ .

- (a) Show that  $g: \mathbb{R} \to \mathbb{R}$  is differentiable and compute g'(s) for all  $s \in \mathbb{R}$ .
- (b) Deduce that  $J: V \to \mathbb{R}$  is Gâteaux differentiable at every  $(x, y) \in V$  in the direction of  $(\eta_1, \eta_2) \in V_o$ , and compute  $dJ((x, y); (\eta_1, \eta_2))$ .
- 4. Let V and  $V_o$  be as in Problem 1 and  $J: V \to \mathbb{R}$  as in Problem 3. Define the set

$$\mathcal{A} = \{ (x, y) \in V \mid x(a) = x_o, \ x(b) = x_1, y(a) = y_o, \ \text{and} \ y(b) = y_1 \},\$$

where  $x_o, x_1, y_o$  and  $y_1$  are given real numbers.

Assume that  $(x, y) \in \mathcal{A}$  is an optimizer of J over the class  $\mathcal{A}$ .

(a) Show that

$$dJ((x,y);(\eta_1,\eta_2)) = 0,$$
 for all  $(\eta_1,\eta_2) \in V_o.$ 

(b) Show that (x, y) must be solution of the system of equations

$$\begin{cases} \frac{d}{dt}[F_p(t,x,y,\dot{x},\dot{y})] &= F_x(t,x,y,\dot{x},\dot{y}); \\\\ \frac{d}{dt}[F_q(t,x,y,\dot{x},\dot{y})] &= F_y(t,x,y,\dot{x},\dot{y}). \end{cases}$$

5. Let  $V = C^1([0,1], \mathbb{R}^2), V_o = C_o^1([0,1], \mathbb{R}^2)$  and

$$\mathcal{A} = \{ (x, y) \in V \mid x(0) = x_o, \ x(1) = x_1, y(0) = y_o, \ \text{and} \ y(1) = y_1 \},\$$

where  $x_o, x_1, y_o$  and  $y_1$  are given real numbers.

Define the functional  $J \colon V \to \mathbb{R}$  by

$$J((x,y)) = \int_0^1 \sqrt{(\dot{x}(t))^2 + (\dot{y}(t))^2} \, dt, \quad \text{for all } (x,y) \in V.$$

Consider the optimization problem: Find  $(x, y) \in \mathcal{A}$  such that

$$J((x,y)) \leq J(u,v), \quad \text{for all } (u,v) \in \mathcal{A}$$

- (a) Give necessary conditions for  $(x, y) \in \mathcal{A}$  to be a solution of the optimization problem.
- (b) Give a candidate  $(x, y) \in \mathcal{A}$  for a solution of the optimization problem. Give a geometric interpretation of your result.