

# Witnesses and local cohomology

Vin de Silva  
(joint work with Gunnar Carlsson)

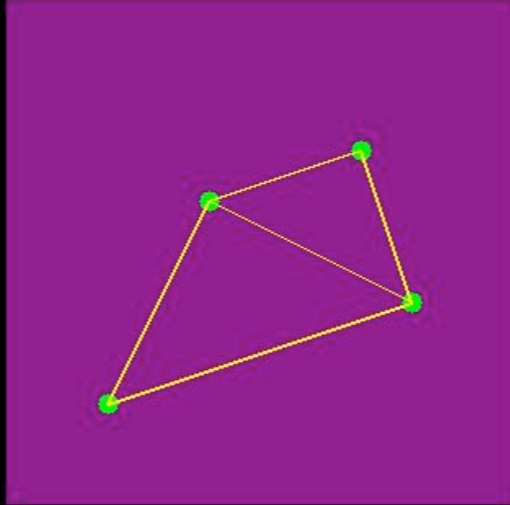
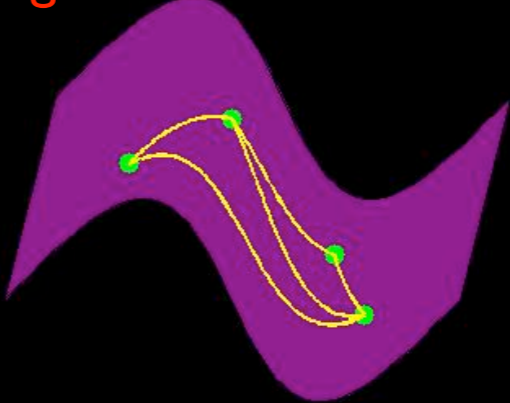
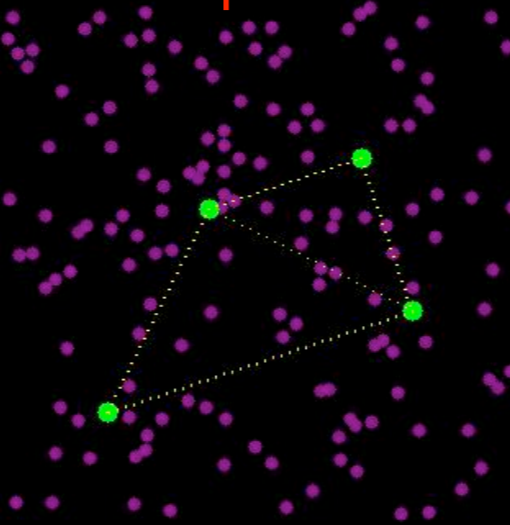
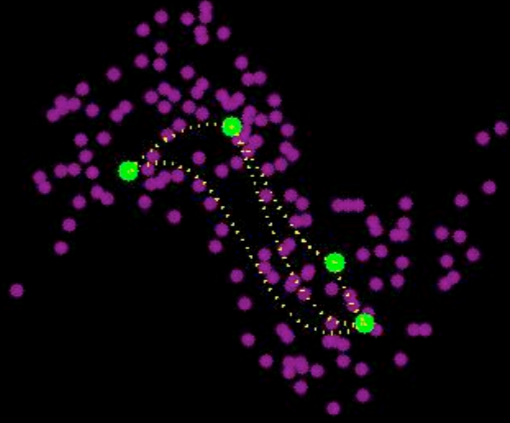
DARPA TDA meeting, Santa Barbara, May 8–10, 2006



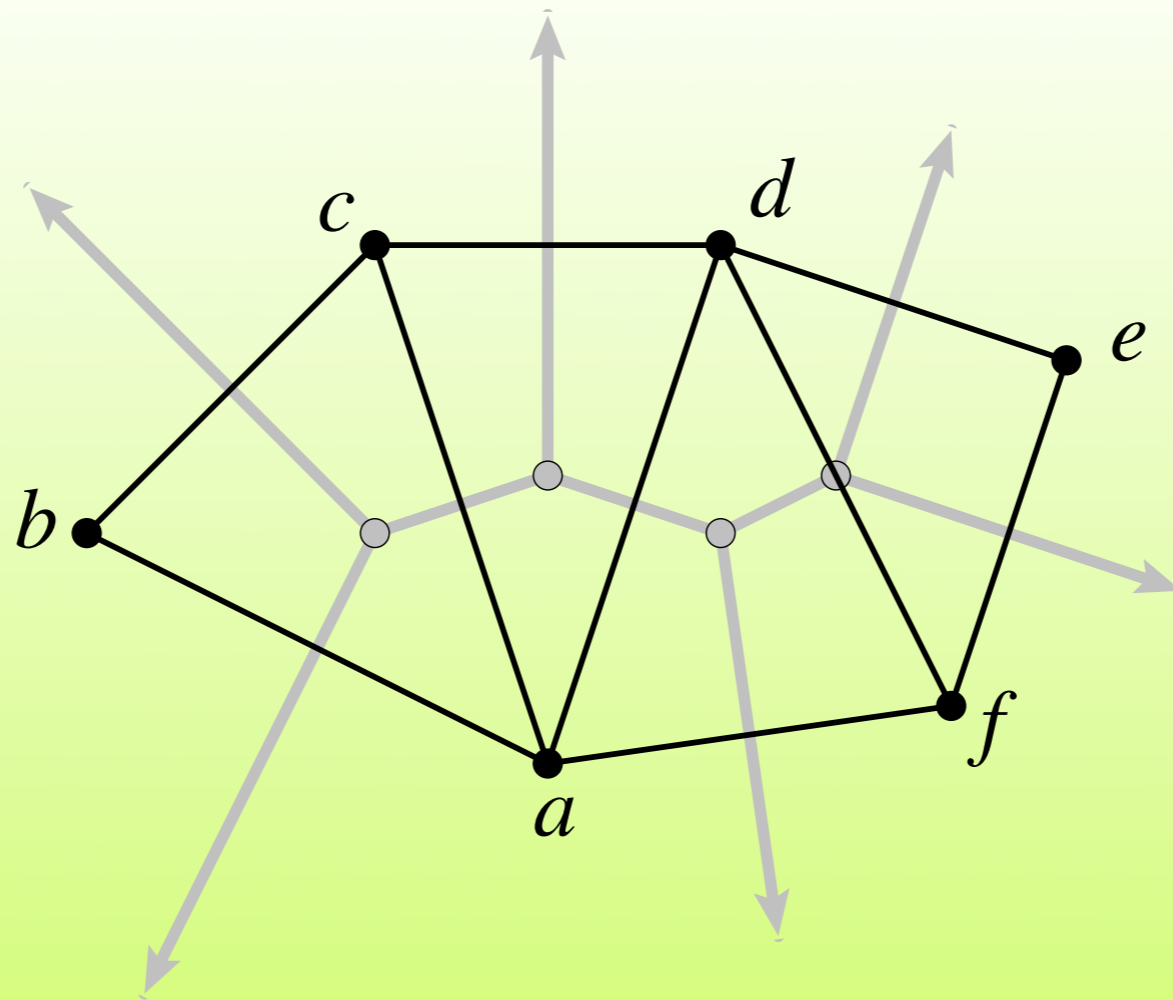
# Reconstruction problem

- Finite point-set  $B$  sampled from unknown manifold  $X$
- Recover the homotopy type/topology of  $X$  from  $B$
  
- Pick a small subset  $A \subset B$
- Build a simplicial complex with vertices  $A$
- Use  $B$  as an approximation to  $X$

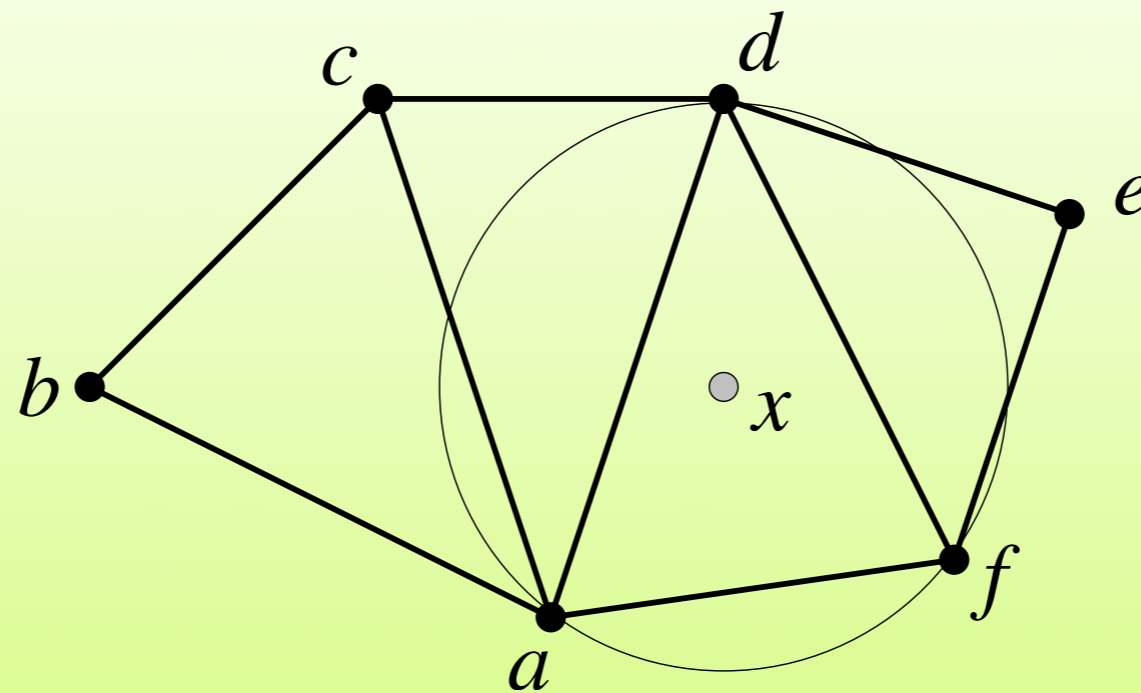
# Witness complex paradigm(I)

	flat	curved
continuous	<p>Delaunay triangulation</p>  A flat purple square with four green points. Yellow lines connect the points to form a Delaunay triangulation.	<p>restricted Delaunay triangulation</p>  A curved purple surface with four green points. Yellow lines connect the points to form a restricted Delaunay triangulation.
point cloud	<p>witness complex</p>  A flat purple point cloud with four green points. Dotted yellow lines connect the points to form a witness complex.	<p>witness complex</p>  A curved purple point cloud with four green points. Dotted yellow lines connect the points to form a witness complex.

# Delaunay triangulation



# Strong witnesses



# Strong witnesses

- $x \in \mathbf{R}^n$  is a **strong witness** for  $S \subseteq A$

$$\Leftrightarrow d(x,a) \leq d(x,b) \text{ for all } a \in S, b \in A$$

$x$  is necessarily equidistant from the vertices of  $S$

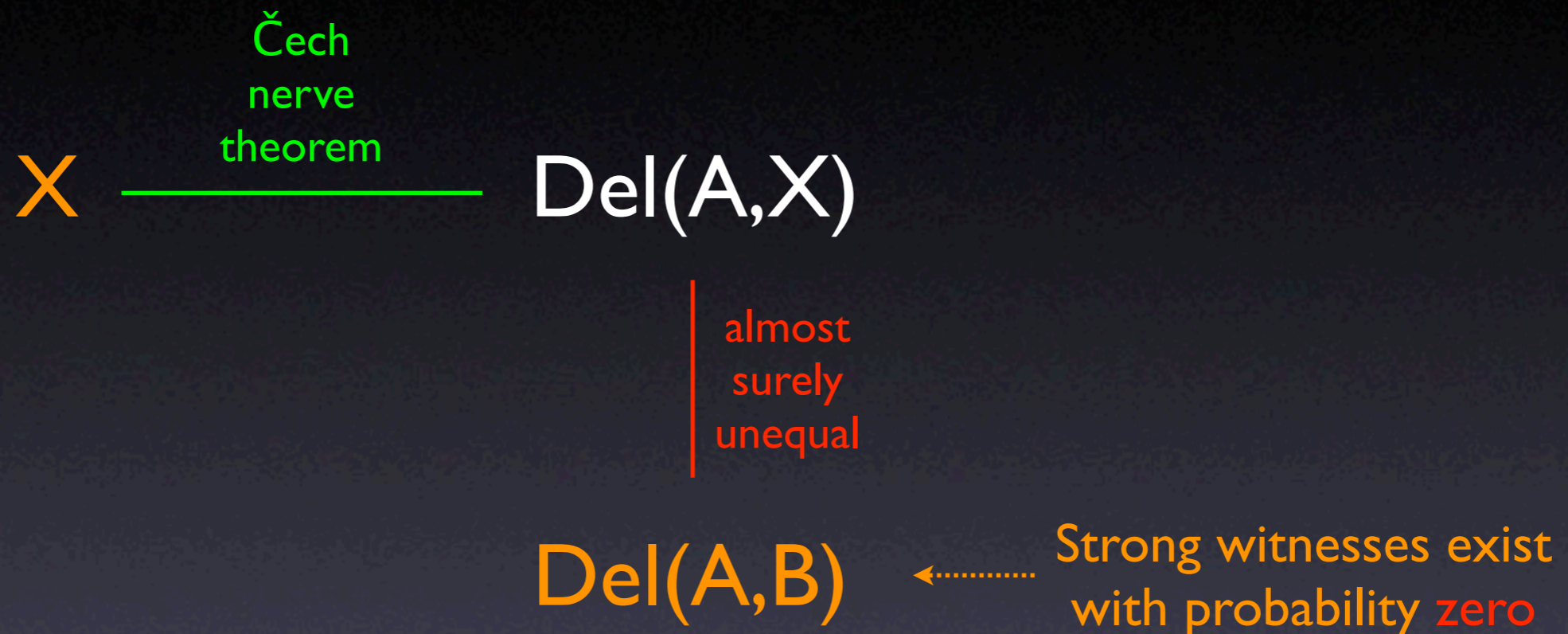
# Witness complexes

- strong witness complex

$S \in \text{Del}(A, X) \Leftrightarrow S$  has a strong witness in  $X$

- $\text{Del}(A, \mathbf{R}^n) =$  Delaunay triangulation
- $\text{Del}(A, X) =$  restricted Delaunay triangulation

# Witness complex paradigm(I)



Green means “plausibly equal”

Red means “clearly unequal”

# Strong and weak witnesses

- $x \in \mathbf{R}^n$  is a **strong witness** for  $S \subseteq A$

$$\Leftrightarrow d(x,a) \leq d(x,b) \text{ for all } a \in S, b \in A$$

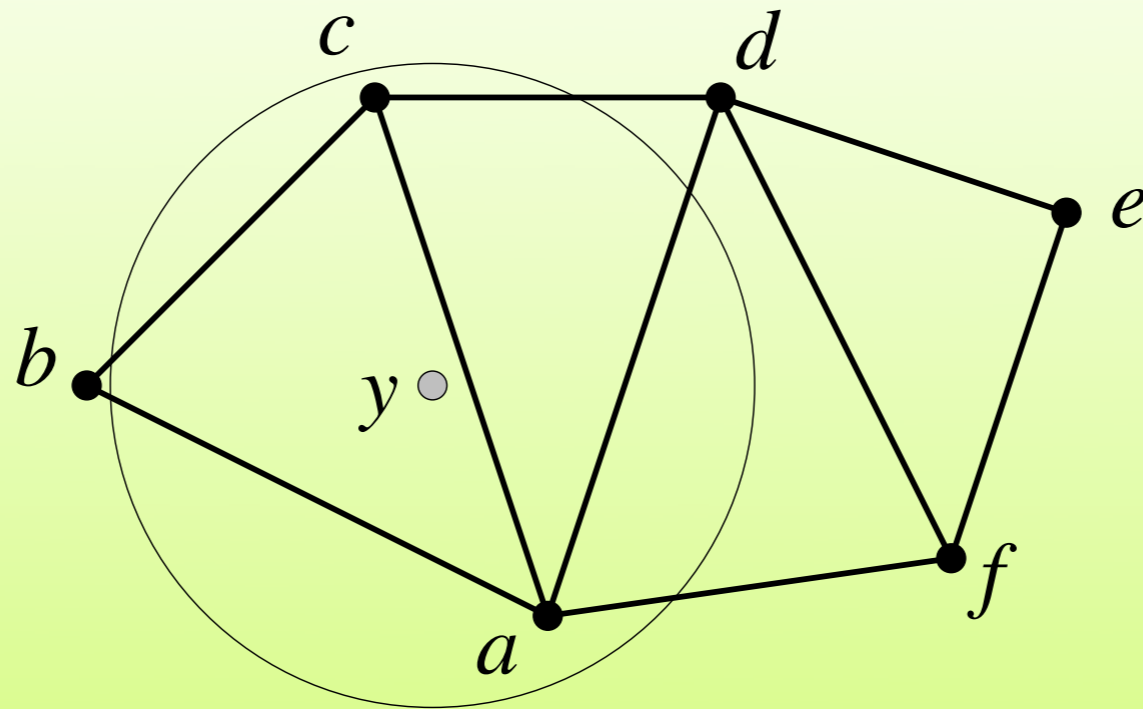
$x$  is necessarily equidistant from the vertices of  $S$

- $x \in \mathbf{R}^n$  is a **weak witness** for  $S \subseteq A$

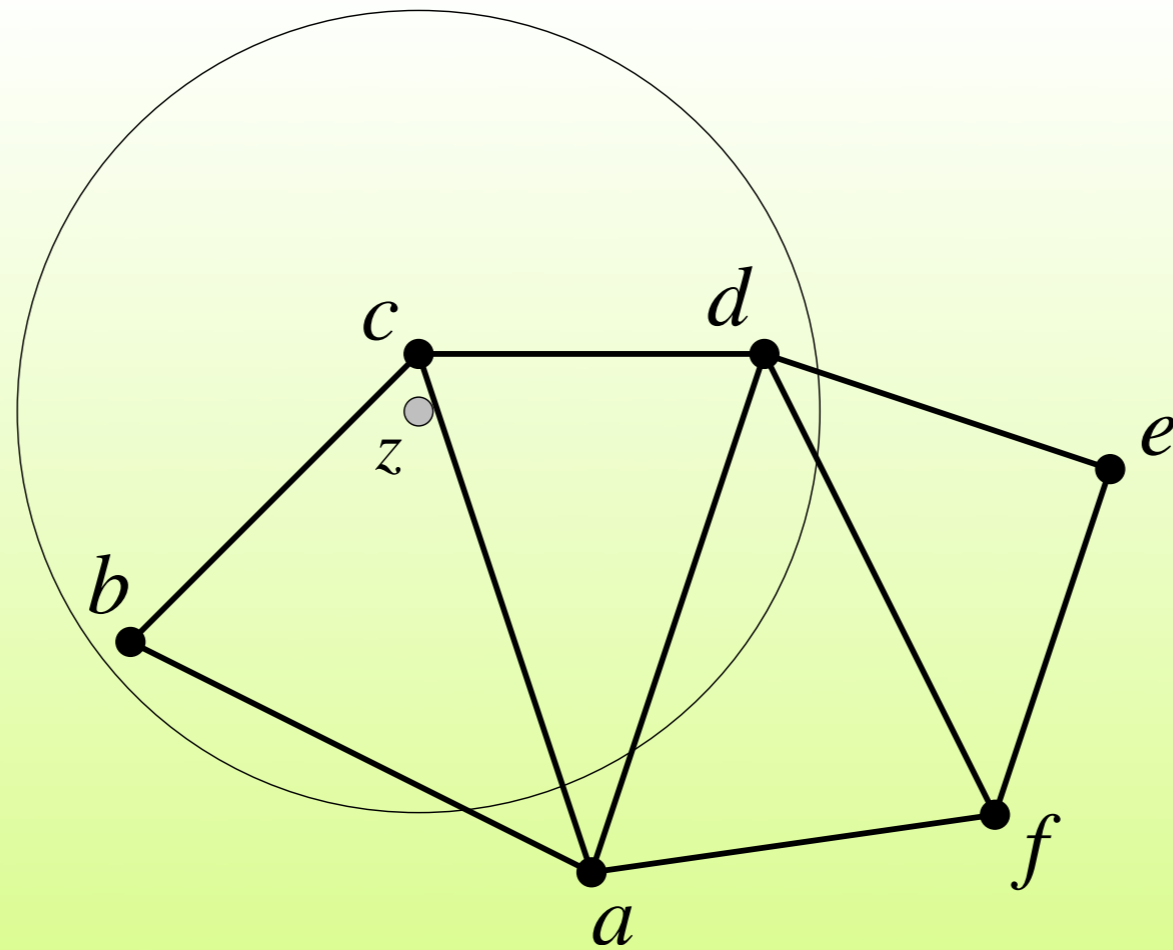
$$\Leftrightarrow d(x,a) \leq d(x,b) \text{ for all } a \in S, b \in A - S$$

$x$  need not be equidistant from the vertices of  $S$

# Weak witnesses



# Weak witnesses



# Witness complexes

- strong witness complex

$S \in \text{Del}(A, X) \Leftrightarrow S$  has a strong witness in  $X$

- $\text{Del}(A, \mathbf{R}^n) =$  Delaunay triangulation

- $\text{Del}(A, X) =$  restricted Delaunay triangulation

- weak witness complex

$S \in \text{Del}^w(A, X) \Leftrightarrow$  every  $T \subseteq S$  has a weak witness in  $X$

# The weak witnesses theorem

$$\text{Del}(A, \mathbf{R}^n) = \text{Del}^w(A, \mathbf{R}^n)$$

$S \subseteq A$  has a strong witness

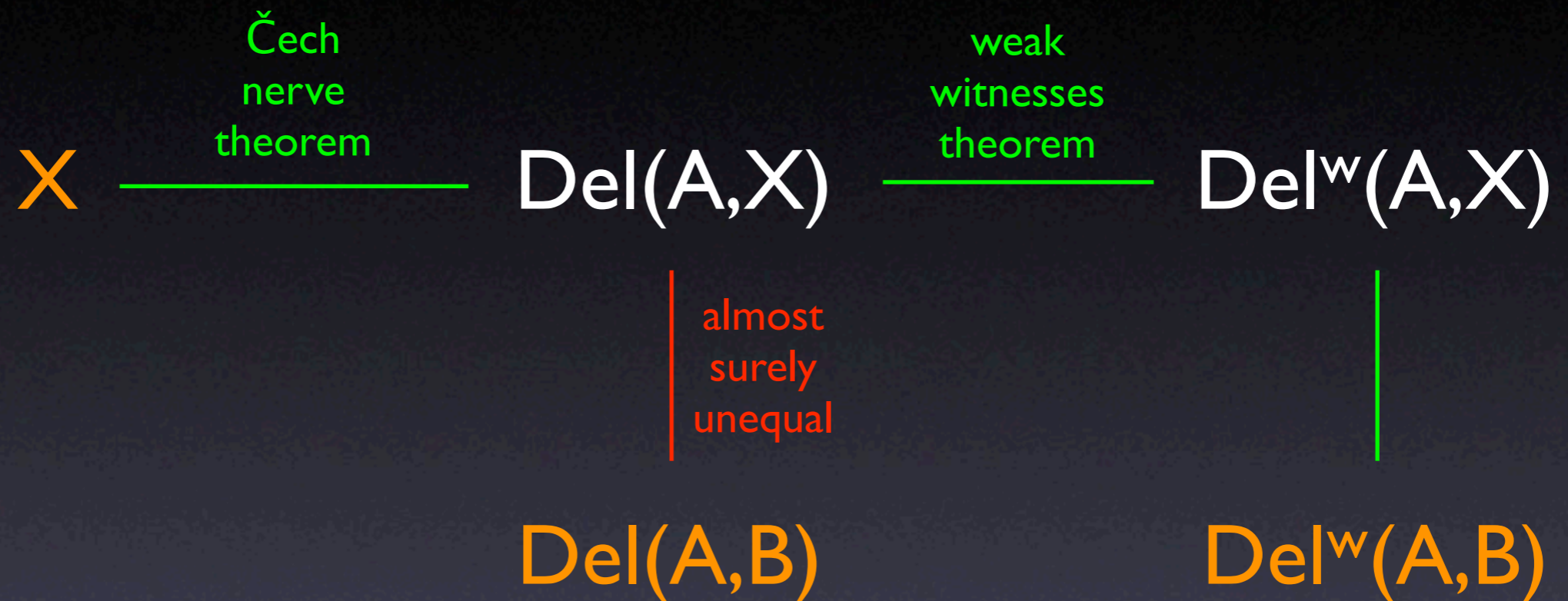


every  $T \subseteq S$  has a weak witness

⇒ trivial

⇐ construct strong witness in convex hull of weak witnesses

# Witness complex paradigm(2)



Green means “plausibly equal”

Red means “clearly unequal”

# The weak witnesses theorem

$$\text{Del}(A, \mathbf{R}^n) = \text{Del}^w(A, \mathbf{R}^n)$$

$S \subseteq A$  has a strong witness



every  $T \subseteq S$  has a weak witness

⇒ trivial

⇐ construct strong witness in convex hull of weak witnesses

# Voronoi convexity

- Under the following assumptions...
  - topological space  $X$ , set  $A$
  - $\forall x, y \in X, \exists$  connected  $\gamma(x, y) \ni x, y$   
convex hull of  $\{x, y\}$
  - $\forall a \in A, \exists$  continuous function  $d(a, x)$
  - $\forall x, y \in X$ , the Voronoi half-space

$$R(a, b) = \{x \in X \mid d(a, x) \leq d(b, x)\}$$

is  $\gamma$ -convex (i.e. closed under  $\gamma$ )

- ...it follows that  $\text{Del}(A, X) = \text{Del}^w(A, X)$

# Examples

- **Voronoi convexity** is satisfied by:
  - $A \subset X = \mathbf{R}^n$ ,  $d(a,x) = |a-x| =$  geodesic metric
  - $A \subset X = \frac{1}{2}\mathbf{S}^n$  (hemisphere),  $d(a,x) =$  geodesic metric
  - $A \subset X = \mathbf{H}^n$  (hyperbolic space),  $d(a,x) =$  geodesic metric
  - $A \subset X = \mathbf{T}$  (tree),  $d(a,x) =$  geodesic metric
  - $A \subset X = \mathbf{R}^{p,q}$ ,  $d(a,x) = |a-x|^2 =$  Minkowski square norm
  - $A \subset X = \mathbf{R}^{p,q}$ ,  $d(a,x) = a*x =$  Minkowski inner product
  - $X = \mathbf{R}^n$ ,  $A \subset \mathbf{R}^n \times \mathbf{R}$ ,  $d((a,c),x) = a.x - c$  linear inequalities

# Laguerre diagrams

Weight schemes which satisfy **Voronoi convexity**

- **Euclidean**

$$D(a, w(a), x) = \frac{1}{2}|a-x|^2 - w(a)$$

- **Spherical (restrict to hemisphere)**

$$D(a, w(a), x) = -e^{w(a)} \cos(\theta(a,x))$$

- **Hyperbolic**

$$D(a, w(a), x) = e^{-w(a)} \cosh(u(a,x))$$

(Spherical Laguerre diagrams due to Sugihara, 2002)

# Tolerance $\epsilon$

- $x \in \mathbf{R}^n$  is an + **strong  $\epsilon$ -witness** for  $S \subseteq A$   
 $\Leftrightarrow d(x,a) \leq d(x,b) + \epsilon$ , for all  $a \in S, b \in A$
- $x \in \mathbf{R}^n$  is an **weak  $\epsilon$ -witness** for  $S \subseteq A$   
 $\Leftrightarrow d(x,a) \leq d(x,b) + \epsilon$ , for all  $a \in S, b \in A - S$

# $\epsilon$ -witness complexes

- strong  $\epsilon$ -witness complex

$S \in \text{Del}(A, X; \epsilon) \Leftrightarrow S$  has a strong  $\epsilon$ -witness in  $X$

- weak  $\epsilon$ -witness complex

$S \in \text{Del}^w(A, X; \epsilon) \Leftrightarrow$  every  $T \subseteq S$  has a weak  $\epsilon$ -witness in  $X$

Filtered complexes: use persistent homology!  
(Edelsbrunner, Letscher, Zomorodian 2000)

# Weak $\epsilon$ -witnesses theorem

- Under the following assumptions...  
(strong Voronoi convexity)
  - topological space  $X$ , set  $A$
  - $\forall x, y \in X, \exists$  connected  $\gamma(x, y) \ni x, y$
  - $\forall a \in A, \exists$  continuous function  $L(a, x)$
  - $\forall x, y \in X$ , the  $\epsilon$ -Voronoi half-space

$$R_\epsilon(a, b) = \{x \in X \mid L(a, x) \leq L(b, x) + \epsilon\}$$

is  $\gamma$ -convex (i.e. closed under  $\gamma$ )

- ...it follows that  $\text{Del}(A, X; \epsilon) = \text{Del}^w(A, X; \epsilon)$

# Examples

The **weak  $\epsilon$ -witnesses** theorem applies in the following cases:

- **Euclidean**

$$L(a, x) = \frac{1}{2}|a-x|^2$$

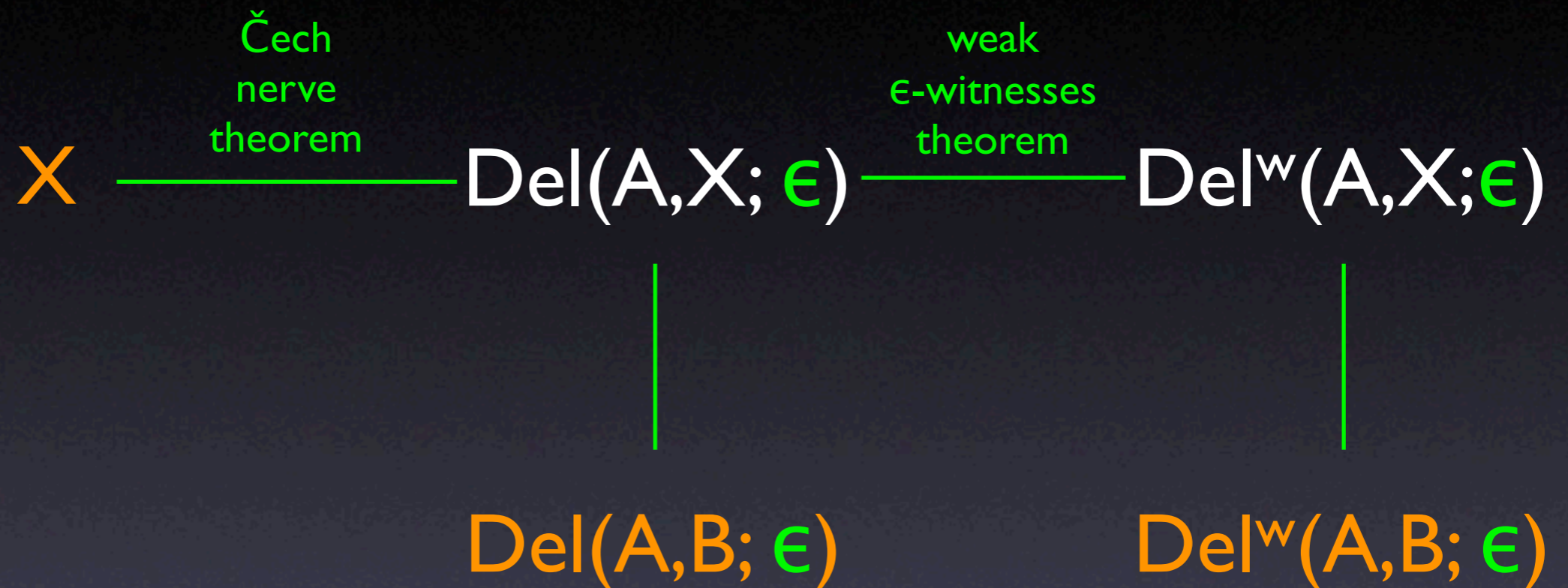
- **Spherical (restrict to subset of diameter less than  $90^\circ$ )**

$$L(a, x) = \log \sec(\theta(a, x))$$

- **Hyperbolic**

$$L(a, x) = \log \cosh(u(a, x))$$

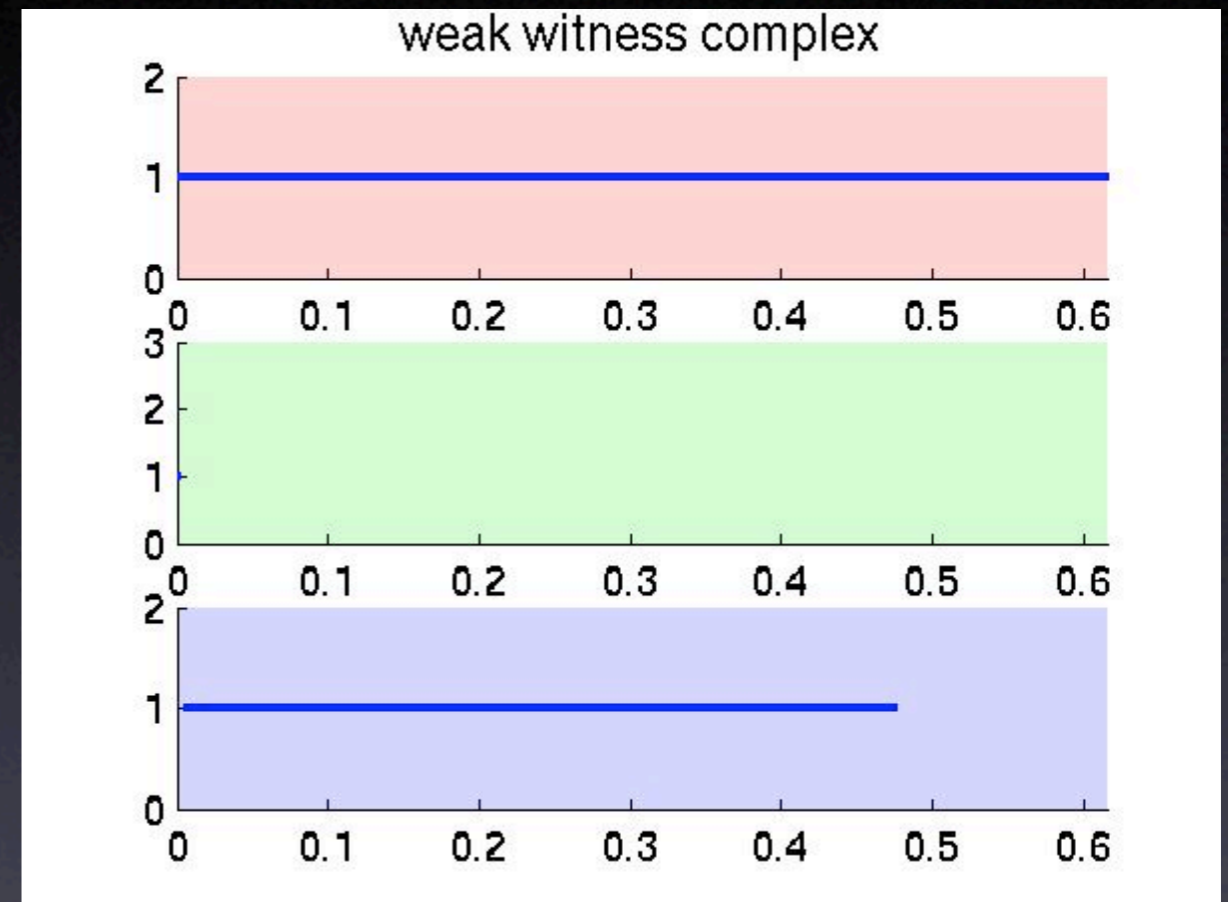
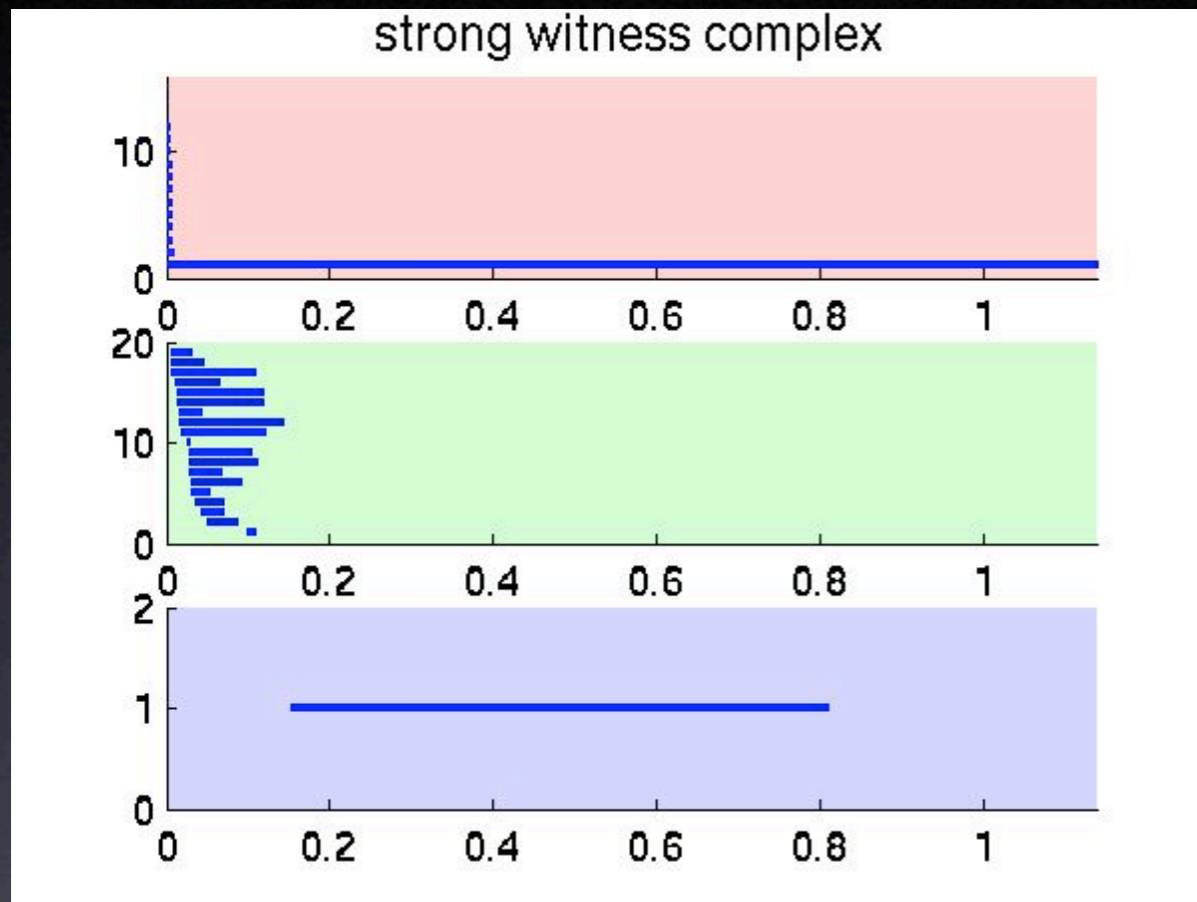
# Witness complex paradigm(3)



Green means “plausibly equal”

Red means “clearly unequal”

# Comparing **strong** and **weak**



Data points sampled from 2-sphere



# Persistent homology

- Persistent homology algorithm (ELZ2000):
  - **Given** filtered simplicial complex  $\{K_t, \rightarrow\}$
  - **Input**  $(S, \partial S)$  in order of appearance of  $S$

Note: When  $S$  enters the filtration, the simplices of  $\partial S$  are already there.

- **Output** persistent homology

$$\{H_*(K_t), \rightarrow\}$$

- What happens if you input the cells in reverse order?

# Persistent relative cohomology

- Persistent homology algorithm (ELZ2000):
  - **Given** filtered simplicial complex  $\{K_t, \rightarrow\}$
  - **Input**  $(S, \delta S)$  in order of appearance of  $S$

When  $S$  enters the reversed filtration, the simplices of  $\delta S$  are already there.

- **Output** persistent relative cohomology

$$\{H^*(K, K_t), \rightarrow\}$$

(at time  $t$ , the missing cells are those of  $K_t$ ).

- Next: exploit this for local homology calculations.

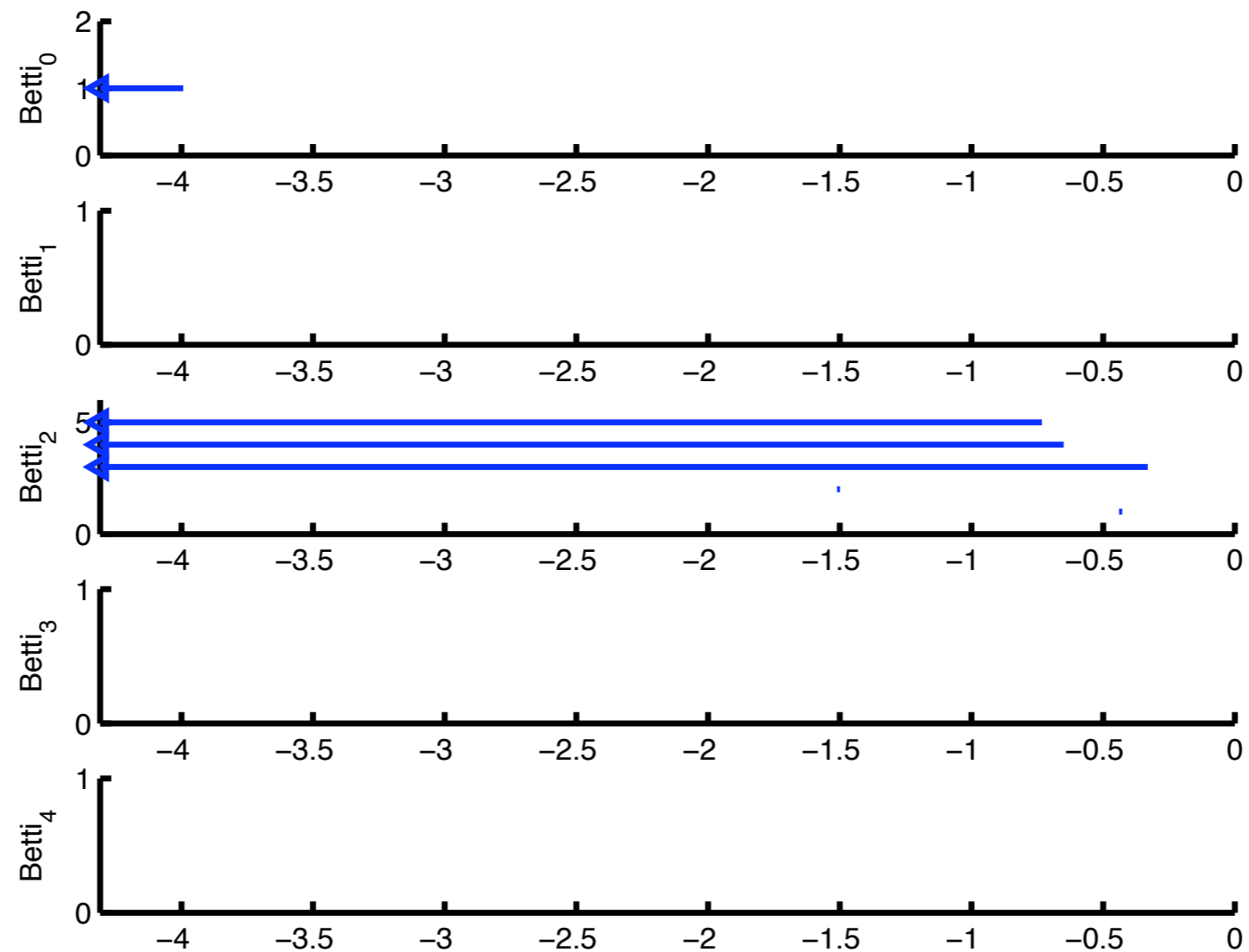
# Local cohomology

- The local structure of  $X$  near a point  $x_0$  is measured in homology by  $H^*(X, X-x_0)$ .
- Define a filtration  $X_t$  for  $t < 0$  which approaches  $X-x_0$  as  $t \rightarrow 0$  from below:

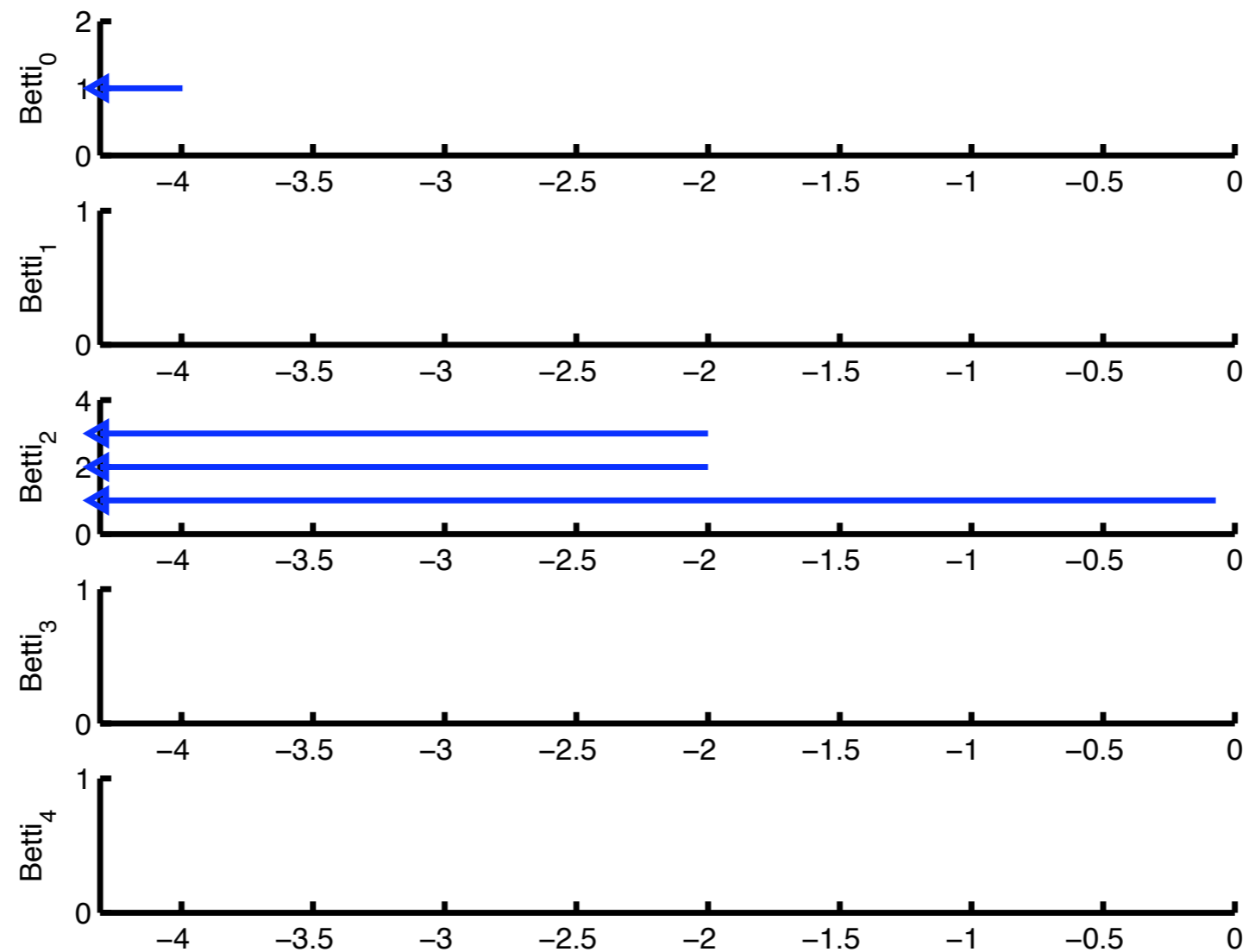
$$X_t = \{x \text{ in } X \mid d(x, x_0) > |t|\}$$

- For fixed  $\epsilon$  and varying  $t$ , compute the persistent relative cohomology of  $\text{Del}^w(A, B_t; \epsilon)$ .
- The  $t$ -value of a given simplex  $S$  is the smallest  $t$  for which all the witnesses for  $T \subseteq S$  exist.

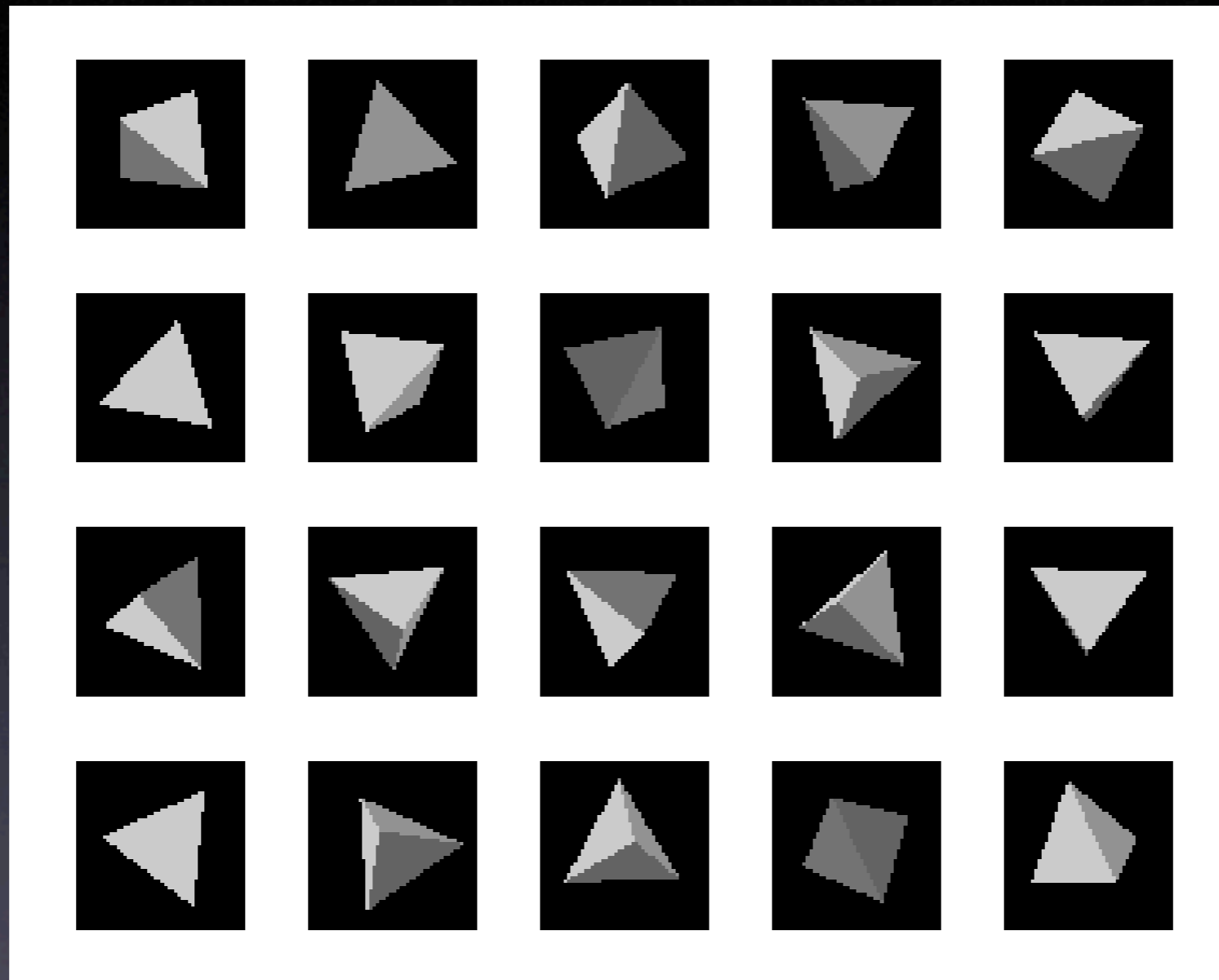
# Two spheres meet on a circle



# Two spheres meet on a circle

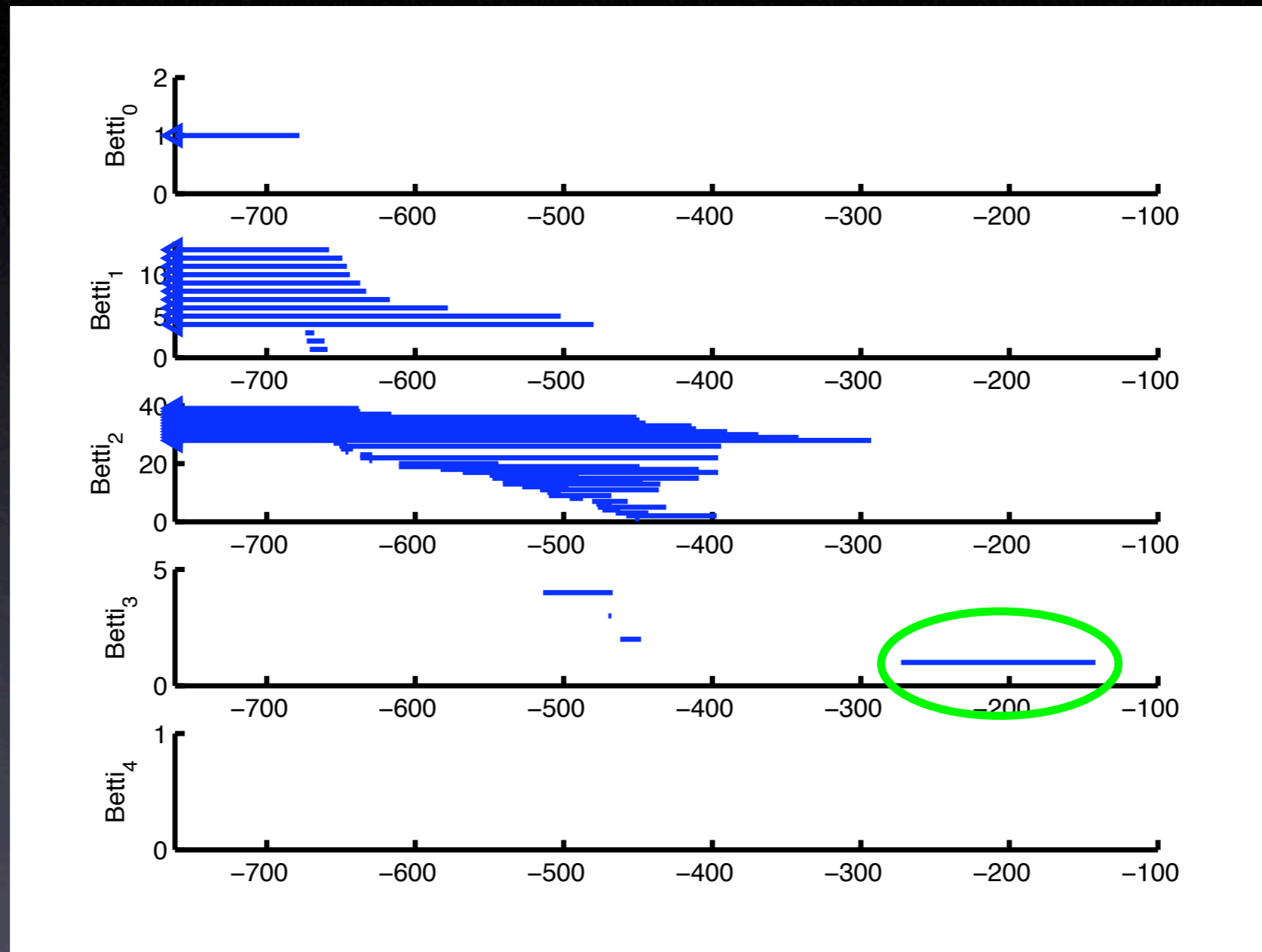


# Space of tetrahedron images



Space of rotations =  $SO(3)$  is **3-dimensional**

# Space of tetrahedron images



Confession: I cheated a bit (by **cherry**-picking)

The End